Brylawski – Lucas theorem of uniquely representable linear matroids



By Alexander Erick Trofimoff
Graduate Research Assistant
PhD program Drexel U.
ECE dept Summer 2013

Bibliography

- Brilawski T, Lucas D, Uniquely representable combinatorial geometries, 1973
- Wild M., The Asymptotic number of inequivalent Binary codes and nonisomorphic binary matroids, May 1999
- Wild M., Consequences of the Brylawski-Lucas Th for binary matroids, 1996
- Wild M, Enumeration of binary and Ternary Matroids and other applications of the Brylawski-Lucas Theorem, Preprint, 1994

- ✓ Is matrix representation of Matroids Unique? (Introduction)
- Linear Space dependency and Matrices
- Row, Projective and Geometric equivalent matrix representations.
- Matroids Matrix and Bipartite graph representations.
- Basic incidence matrices and connectivity on Bipartite graphs
- Reduced B-basic matrix for matroid **G**
- Geometry equivalence subdeterminants criteria
- Matroid projective equivalent distinct matrix representations.
- Matroid row equivalent classes.

Is matrix representation of matroids unique?

Brylawski Lucas Theorem

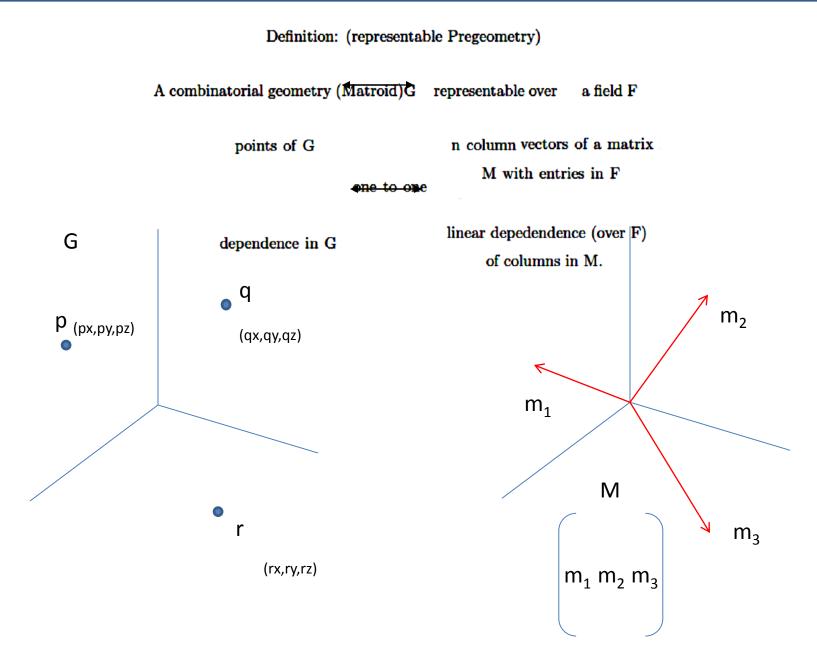
Uniquely representable combinatorial geometries T.Brylawski and D.Lucas problem

how a combinatorial abstract geometry (Matroid), can be representable

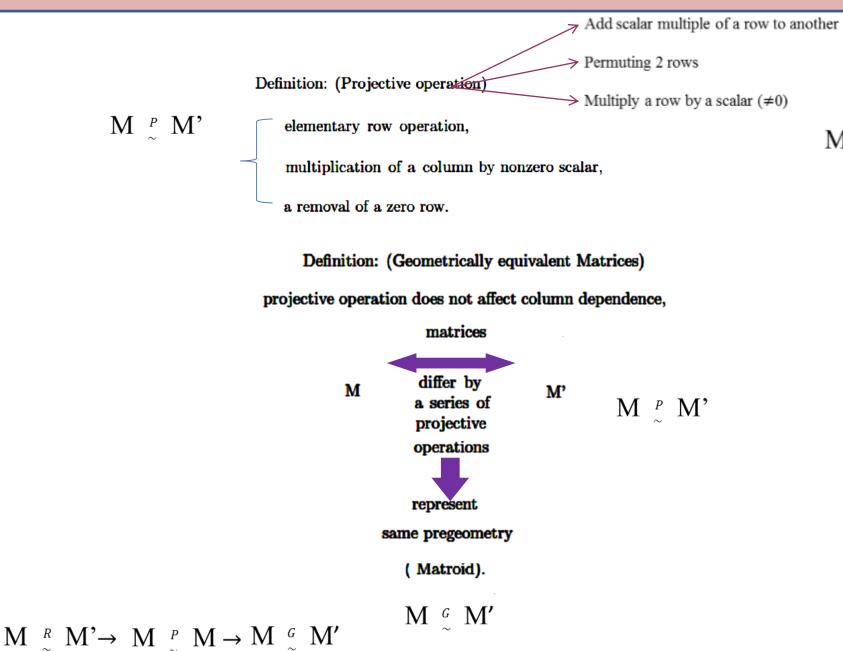
in unique way, as a subset of a projective space

and what do these representations signify?

- Is matrix representation of Matroids Unique? (Introduction)
- **✓ Linear Space dependency and Matrices**
- **✓** Row, Projective and Geometric equivalent matrix representations .
- Coordinatinatization Matroids Matrix and Bipartite graph representations.
- Basic incidence matrices and connectivity on Bipartite graphs
- Reduced B-basic matrix for matroid G
- Geometry equivalence subdeterminants criteria
- Matroid projective equivalent distinct matrix representations.
- Matroid row equivalent classes.



Row, Projective and Geometric equivalence among matrix representations

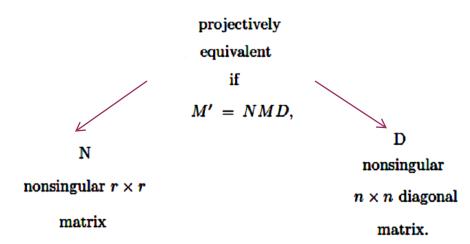


Projective equivalence in between matrix representations

$$M \stackrel{P}{\sim} M'$$

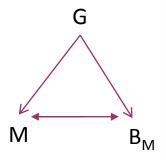
Definition: (Projectively equivalent matrices)

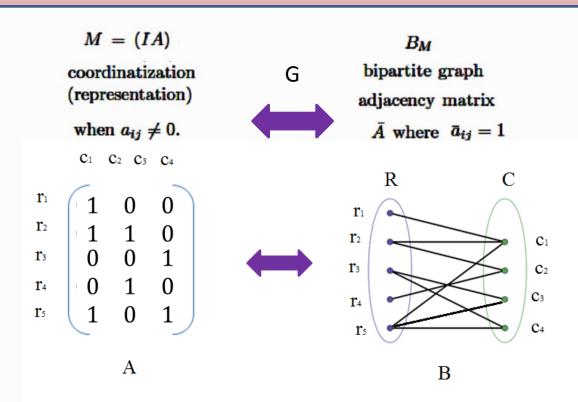
Two matrices



- Is matrix representation of Matroids Unique? (Introduction)
- Linear Space dependency and Matrices
- Row, Projective and Geometric equivalent matrix representations.
- **✓** Coordinatinatization Matroids Matrix and Bipartite graph representations.
- Basic incidence matrices and connectivity on Bipartite graphs
- Reduced B-basic matrix for matroid G
- Geometry equivalence subdeterminants criteria
- Matroid projective equivalent distinct matrix representations.
- Matroid row equivalent classes.

Coordinatization among Matrix representation and Bipartite graph representation





Definition: (Coordinatizing path of M or A.)

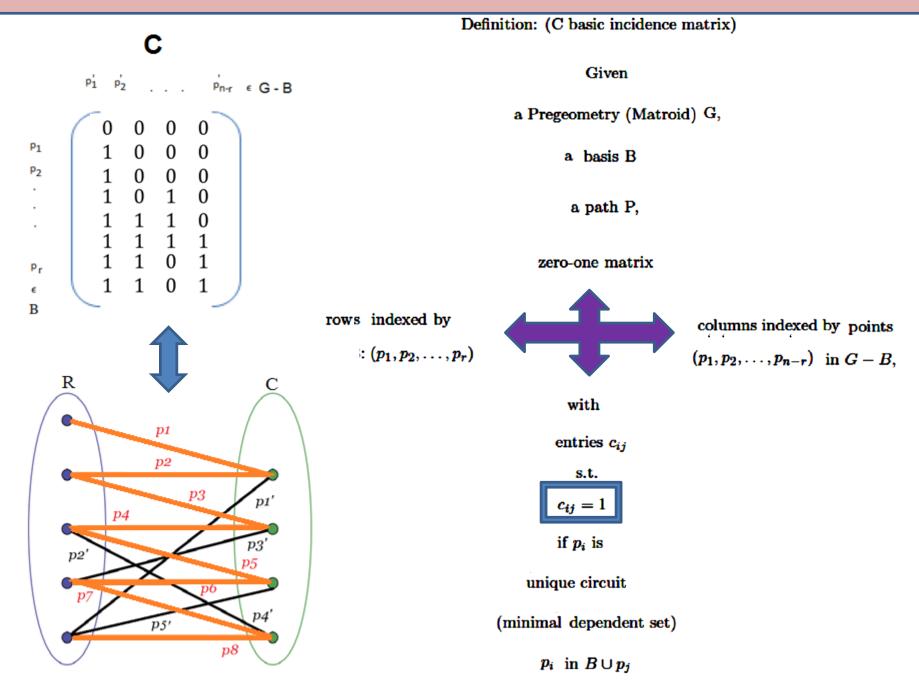
A basis of B_M

Definition: (Coordinatizing circuit of M or A.)

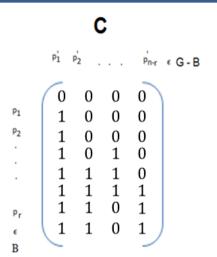
A basic circuit of B_M

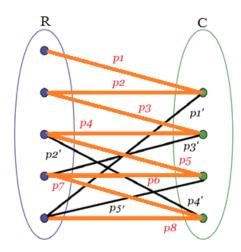
- Is matrix representation of Matroids Unique? (Introduction)
- Linear Space dependency and Matrices
- Row, Projective and Geometric equivalent matrix representations.
- Matroids Matrix and Bipartite graph representations.
- **✓** Basic incidence matrices and connectivity on Bipartite graphs
- ✓ Reduced B-basic matrix for matroid G
- Geometry equivalence subdeterminants criteria
- Matroid projective equivalent distinct matrix representations.
- Matroid row equivalent classes.

C basic incidence matrix representations.



B basic incidence matrix representation and connectness





geometry(Matroid) G,

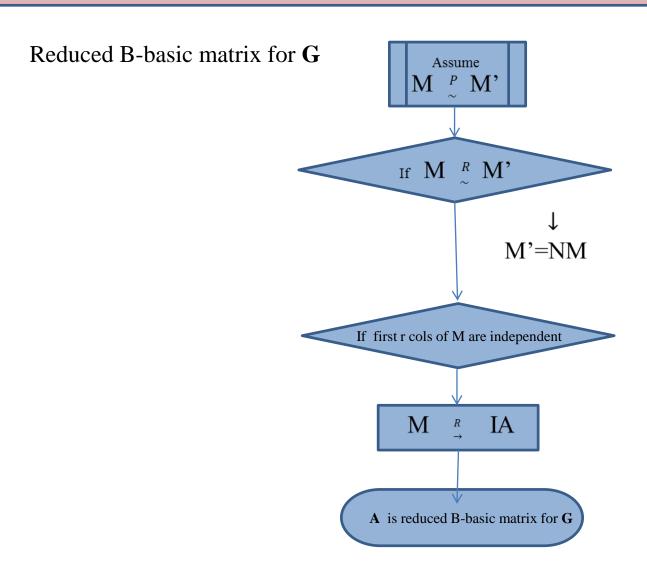
If C is B-basic circuit incidence matrix of G,

then the number of connected components

of G equals
$$r' + c' + k$$
,

r' is the number of zero rows of C,c' is the number of zero columns of C,

k is the number of blocks of C after zero rows and and columns have been eliminated.



- Is matrix representation of Matroids Unique? (Introduction)
- Linear Space dependency and Matrices
- Row, Projective and Geometric equivalent matrix representations.
- Matroids Matrix and Bipartite graph representations.
- Basic incidence matrices and connectivity on Bipartite graphs
- Reduced B-basic matrix for matroid **G**
- **✓** Geometry equivalence subdeterminants criteria
- **✓** Matroid projective equivalent distinct matrix representations.
- Matroid row equivalent classes.

Geometric equivalence and subdeterminants of adjacent and incidence matrices.

Proposition:

If
$$M = IA$$
 and $M' = IA'$

$$M \stackrel{G}{\sim} M'$$

iff

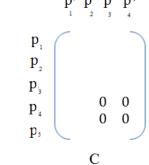
every subdeterminant of A
$$D \equiv 0$$

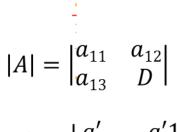
exactly when the

of G

subdeterminant of
$$A'$$
 $D' \equiv 0$

entry
$$a_{ij} = 0 = a'_{ij}$$
iff
 $c_{ij} = 0$
circuit incidence matrix





$$|A'| = \begin{vmatrix} a'_{11} & a'12 \\ a'13 & D' \end{vmatrix}$$

Proposition:

Let G be a matroid (pregeometry)

rank r cardinality n,

k connected components.

P coordinatizing path of A

If
$$M = IA$$
represents G over F
$$if \mid F \mid = q,$$

$$(q - I)^{n-k} \text{ distinct matrices}$$

 \exists

$$[IA'] = \mathbf{M}' \stackrel{P}{\sim} \mathbf{M}$$

$$(q^r-I)(q^r-q)\dots(q^r-q^{r-1})(q-I)^{n-k}$$

distinct $r \times n$ matrices,

$$PA' = M' \sim M$$

- Is matrix representation of Matroids Unique? (Introduction)
- Linear Space dependency and Matrices
- Row, Projective and Geometric equivalent matrix representations.
- Matroids Matrix and Bipartite graph representations.
- Basic incidence matrices and connectivity on Bipartite graphs
- Reduced B-basic matrix for matroid **G**
- Geometry equivalence subdeterminants criteria
- Matroid projective equivalent distinct matrix representations.
- **✓** Matroid row equivalent classes.

Number of matrices and equivalence classes under row equivalence

Corollary:

If G representable over F, $\mid F \mid = q$,



each projective equivalence class

with

 $PA' \quad r \times n \quad \text{representations}$

is partioned into

 $(q-I)^{n-k}$ distinct row equivalence classes

each class contains $\prod\limits_{i=0,r-1}q^r-q^i$

 $r \times r$ non singular distinct matrices over F_q .